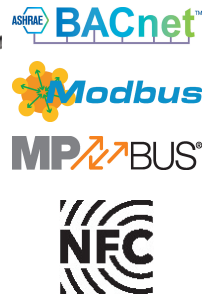
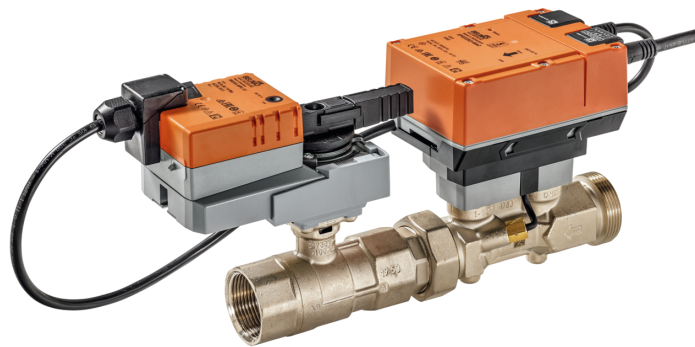


Characterised control valve with sensor-operated flow control, 2-way, Internal and external thread, PN 25 (EPIV)

- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid
- For closed cold and warm water systems
- For modulating control of air-handling and heating systems on the water side
- Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control
- Conversion of active sensor signals and switching contacts
- Measurement of the fluid temperature


**Type Overview**

Type	DN	Rp [""]	G [""]	V'nom [l/s]	V'nom [l/min]	V'nom [m³/h]	kvs theor. [m³/h]	PN
EP015R2+BAC	15	1/2	3/4	0.42	25	1.5	3.2	25
EP020R2+BAC	20	3/4	1	0.69	41.7	2.5	5.3	25
EP025R2+BAC	25	1	1 1/4	0.97	58.3	3.5	8.8	25
EP032R2+BAC	32	1 1/4	1 1/2	1.67	100	6	14.1	25
EP040R2+BAC	40	1 1/2	2	2.78	166.7	10	19.2	25
EP050R2+BAC	50	2	2 1/2	4.17	250	15	30.4	25

kvs theor.: Theoretical kvs value for pressure drop calculation

**Technical data**

<b>Electrical data</b>	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	4 W (DN 15, 20, 25) 5 W (DN 32, 40, 50)
	Power consumption in rest position	3.7 W (DN 15, 20, 25) 3.9 W (DN 32, 40, 50)
	Power consumption for wire sizing	6.5 VA (DN 15, 20, 25) 7.5 VA (DN 32, 40, 50)
	Connection supply / control	Cable 1 m, 6x 0.75 mm²
<b>Data bus communication</b>	Communicative control	BACnet MS/TP Modbus RTU MP-Bus
	Number of nodes	BACnet / Modbus see interface description MP-Bus max. 8
	MP-Bus compatibility mode	If the device is used as a EP..R-(K)MP replacement in an existing MP-Bus system, the unit can be set to the MP compatibility mode. The existing MP client will recognise the device as former EPIV device. The compatibility mode shall not be used for new projects.
<b>Functional data</b>	Operating range Y	2...10 V
	Operating range Y variable	0.5...10 V
	Position feedback U	2...10 V
	Position feedback U note	Max. 1 mA

<b>Functional data</b>	Position feedback U variable	0...10 V 0.5...10 V	
	Sound power level Motor	35 dB(A) (DN 15, 20, 25, 32, 40) 45 dB(A) (DN 50)	
	V'max adjustable	25...100% of V'nom	
	Control accuracy	±5% (of 25...100% V'nom)	
	Control accuracy note	±10% (of 25...100% V'nom) @ Glycol 0...60% vol.	
	Min. controllable flow	1% of V'nom	
	Parametrisation	via NFC, Belimo Assistant App	
	Fluid	Cold and warm water, water with glycol up to max. 60% vol.	
	Fluid temperature	-10...120°C [14...248°F]	
	Close-off pressure Δps	1400 kPa	
	Differential pressure Δpmax	350kPa	
	Differential pressure note	200 kPa for low-noise operation	
	Flow characteristic	equal percentage, optimised in the opening range (switchable to linear)	
	Leakage rate	air-bubble tight, leakage rate A (EN 12266-1)	
	Pipe connection	Internal and external thread	
	Installation orientation	upright to horizontal (in relation to the stem)	
	Servicing	maintenance-free	
	Manual override	with push-button, can be locked	
	<b>Measuring data</b>	Measured values	Flow Fluid temperature in valve unit
		Temperature sensor	Pt1000 - EN 60751, 2-wire technology, inseparably connected integrated in flow sensor
<b>Temperature measurement</b>	Measuring accuracy absolute temperature	± 0.35°C @ 10°C (Pt1000 EN60751 Class B) ± 0.6°C @ 60°C (Pt1000 EN60751 Class B)	
<b>Flow measurement</b>	Measuring principle	Ultrasonic volumetric flow measurement	
	Measuring accuracy flow	±2% (of 20...100% V'nom) @ 20°C / glycol 0% vol.	
	Measuring accuracy flow note	±5% (of 20...100% V'nom) @ glycol 0...60% vol.	
	Min. flow measurement	0.5% of V'nom	
<b>Glycol monitoring</b>	Measurement display glycol	0...60% or >60%	
	Measuring accuracy glycolmonitoring	±4% (0...60%)	
<b>Safety data</b>	Protection class IEC/EN	III, Protective Extra-Low Voltage (PELV)	
	Degree of protection IEC/EN	IP54	
	Pressure equipment directive	CE according to 2014/68/EU	
	EMC	CE according to 2014/30/EU	
	Certification IEC/EN	IEC/EN 60730-1:11 and IEC/EN 60730-2-15:10	
	Quality Standard	ISO 9001	
	Type of action	Type 1	
	Rated impulse voltage supply / control	0.8 kV	
	Pollution degree	3	
	Ambient humidity	Max. 95% RH, non-condensing	
Ambient temperature	-30...50°C [-22...122°F]		

Technical data

<b>Safety data</b>	Storage temperature	-40...80°C [-40...176°F]
<b>Materials</b>	Valve body	Brass
	Flow measuring pipe	Brass body nickel-plated
	Closing element	Stainless steel
	Spindle	Stainless steel
	Spindle seal	EPDM O-ring

Safety notes



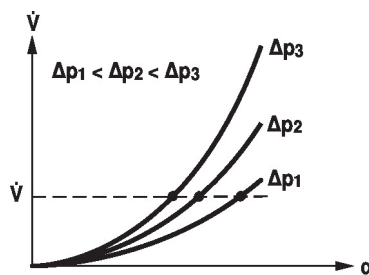
- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

**Operating mode** The HVAC performance device is comprised of three components: characterised control valve (CCV), measuring pipe with flow sensor and the actuator itself. The adjusted maximum flow ( $V'max$ ) is assigned to the maximum control signal (typically 100%). The HVAC performance device can be controlled via communicative signals. The fluid is detected by the sensor in the measuring pipe and is applied as the flow value. The measured value is balanced with the setpoint. The actuator corrects the deviation by changing the valve position. The angle of rotation  $\alpha$  varies according to the differential pressure through the control element (see flow curves).

**Calibration certificate** There is a calibration certificate available in the Belimo Cloud for each device. If needed, it can be downloaded as a PDF through the Belimo Assistant App.

Flow rate curves



**Control characteristics** The fluid velocity is measured in the measuring component (sensor electronics) and converted to a flow rate signal.

The control signal Y corresponds to the power Q via the exchanger, the flow is regulated in the EPIV. The control signal Y is converted into an equal-percentage characteristic curve and provided with the V'max value as the new reference variable w. The momentary control deviation forms the control signal Y1 for the actuator.

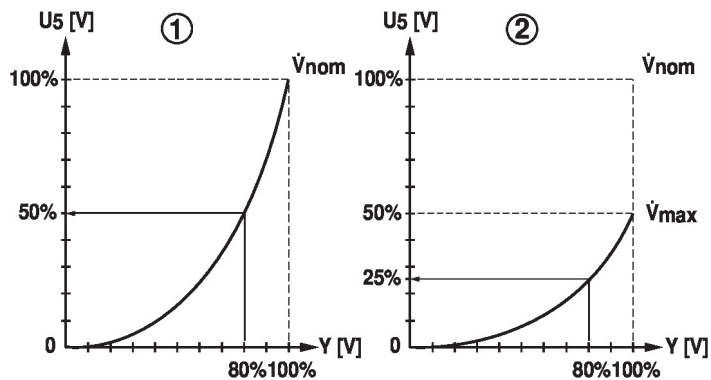
The specially configured control parameters in connection with the precise flow sensor ensure a stable quality of control. They are, however, not suitable for rapid control processes, i.e. for domestic water control. U5 displays the measured flow as voltage (factory setting).

Parametrising V'max with Belimo Assistant App:

U5 refers to the respective V'nom, i.e. if V'max is e.g. 50% of V'nom, then Y = 10 V, U5 = 5 V.

As an alternative, U5 can be used for displaying the valve opening angle (position) or the fluid temperature.

- 1. Standard equal percentage V'max = V'nom / 2. effect V'max < V'nom

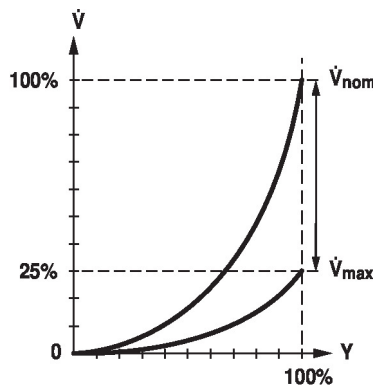


Flow control

V'nom is the maximum possible flow.

V'max is the maximum flow rate which has been set with the highest control signal DDC.

V'max can be set between 25% and 100% of V'nom.



Position control

In this setting, the control signal is assigned to the opening angle of the valve (e.g. Y = 10 V α = 90°).

The result is a pressure-dependent operation similar to that of a conventional valve.

Running time of the motor in this mode is 90 s for 90°.

Product features

**Fluid temperature measurement** By means of the temperature sensor integrated in the flow sensor, the medium temperature is permanently measured. The measured value can be read via the bus system or the analogue feedback signal U. The current measured value is also displayed in the Belimo Assistant App.

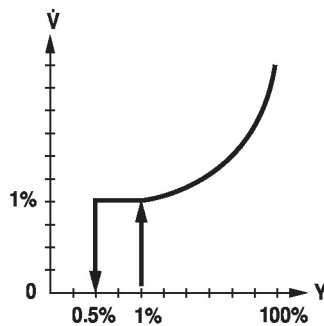
**Creep flow suppression** Given the very low flow speed in the opening point, this can no longer be measured by the sensor within the required tolerance. This range is overridden electronically.

Opening valve

The valve remains closed until the flow required by the control signal DDC corresponds to 1% of V'nom. The control along the flow characteristic is active after this value has been exceeded.

Closing valve

The control along the flow characteristic is active up to the required flow rate of 1% of V'nom. Once the level falls below this value, the flow rate is maintained at 1% of V'nom. If the level falls below the flow rate of 0.5% of V'nom required by the control signal DDC, then the valve will close.



**Converter for sensors** Connection option for a sensor (active or with switching contact). In this way, the analogue sensor signal can be easily digitised and transferred to the bus systems BACnet, Modbus or MP-Bus.

**Control signal inversion** This can be inverted in cases of control with an analogue control signal. The inversion causes the reversal of the standard behaviour, i.e. at a control signal of 0%, regulation is to V'max, and the valve is closed at a control signal of 100%.

**Hydronic balancing** With the Belimo tools, the maximum flow rate (equivalent to 100% requirement) can be adjusted on-site, simply and reliably, in a few steps. If the device is integrated in the management system, then the balancing can be handled directly by the management system.

**Combination analogue - communicative (hybrid mode)** With conventional control by means of an analogue control signal DDC, BACnet, Modbus or MP-Bus can be used for the communicative position feedback.

**Glycol monitoring** Glycol monitoring measures the actual glycol content, which is necessary for safe operation and optimised heat exchange.

**Error readout with analogue position feedback** If the sensor cannot measure the flow due to a sensor error, this is indicated by 0.3 V at the position feedback U. This is only the case if the analogue position feedback U is set to flow and the lower value of the signal range is 0.5 V or more.

**Manual override** Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked).

**High functional safety** The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

**Parts included**

Description	Type
Insulation shell for EPIV / Belimo Energy Valve™ DN 15...25	Z-INSH15
Insulation shell for EPIV / Belimo Energy Valve™ DN 32...50	Z-INSH32
Insulation shell not included in Asia Pacific	

**Accessories**

Mechanical accessories	Description	Type
	Pipe connector DN 15 Rp 1/2", G 3/4"	EXT-EF-15F
	Pipe connector DN 20 Rp 3/4", G 1"	EXT-EF-20F
	Pipe connector DN 25 Rp 1", G 1 1/4"	EXT-EF-25F
	Pipe connector DN 32 Rp 1 1/4", G 1 1/2"	EXT-EF-32F
	Pipe connector DN 40 Rp 1 1/2", G 2"	EXT-EF-40F
	Pipe connector DN 50 Rp 2", G 2 1/2"	EXT-EF-50F
	Insulation shell for EPIV / Belimo Energy Valve™ DN 15...25	Z-INSH15
	Insulation shell for EPIV / Belimo Energy Valve™ DN 32...50	Z-INSH32
	Valve neck extension for ball valve DN 15...50	ZR-EXT-01
	Pipe connector for ball valve with internal thread DN 15 Rp 1/2"	ZR2315
	Pipe connector for ball valve with internal thread DN 20 Rp 3/4"	ZR2320
	Pipe connector for ball valve with internal thread DN 25 Rp 1"	ZR2325
	Pipe connector for ball valve with internal thread DN 32 Rp 1 1/4"	ZR2332
	Pipe connector for ball valve with internal thread DN 40 Rp 1 1/2"	ZR2340
	Pipe connector for ball valve with internal thread DN 50 Rp 2"	ZR2350
Tools	Description	Type
	Belimo Assistant App, Smartphone app for easy commissioning, parametrising and maintenance	Belimo Assistant App
	Converter Bluetooth / NFC	ZIP-BT-NFC
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P

**Electrical installation**


Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS-485 regulations.

Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

Sensor connection: An additional sensor can optionally be connected to the flow sensor. This can be an active sensor with output DC 0...10 V (max. DC 0...32 V with resolution 30 mV) or a switching contact (switching current min. 16 mA @ 24 V). Thus the analogue signal of the sensor can be easily digitised with the flow sensor and transferred to the corresponding bus system.

Analogue output: An analogue output (wire 5) is available on the flow sensor. It can be selected as 0...10 V, 0.5...10 V, 2...10 V or user defined. For example, the flow rate or the temperature of the temperature sensor (Pt1000 - EN 60751, 2-wire technology) can be output as an analogue value.

**Wire colours:**

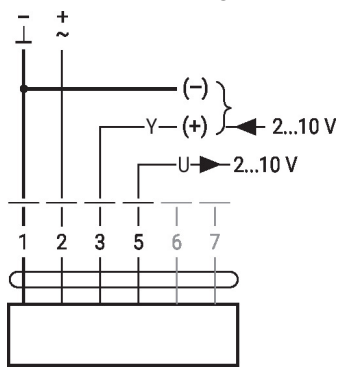
- 1 = black
- 2 = red
- 3 = white
- 5 = orange
- 6 = pink
- 7 = grey

**Functions:**

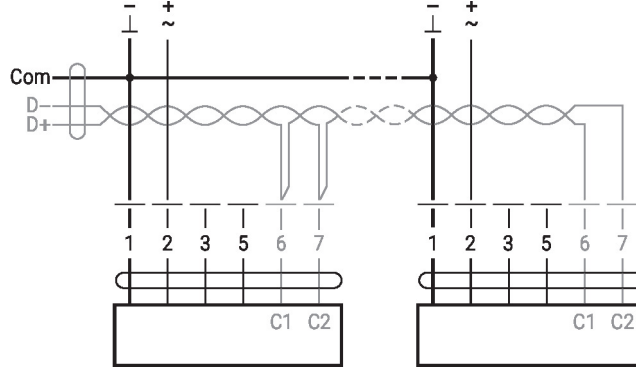
- C1 = D- = A (wire 6)
- C2 = D+ = B (wire 7)

### Electrical installation

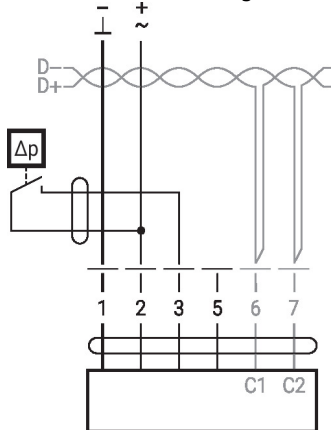
AC/DC 24 V, modulating



BACnet MS/TP / Modbus RTU

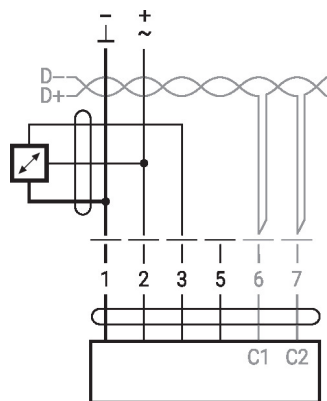


Connection with switching contact, e.g.  $\Delta p$  monitor



Switching contact requirements:  
The switching contact must be able to switch a current of 16 mA at 24 V accurately.

Connection with active sensor, e.g. 0...10 V @ 0...50°C

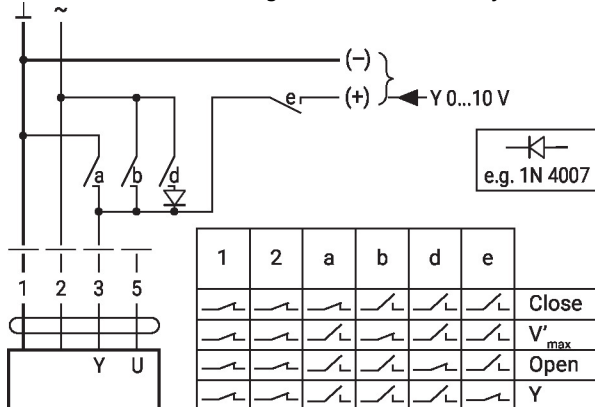


Possible voltage range: 0...32 V  
Resolution 30 mV

### Functions

Functions with specific parameters (parametrisation necessary)

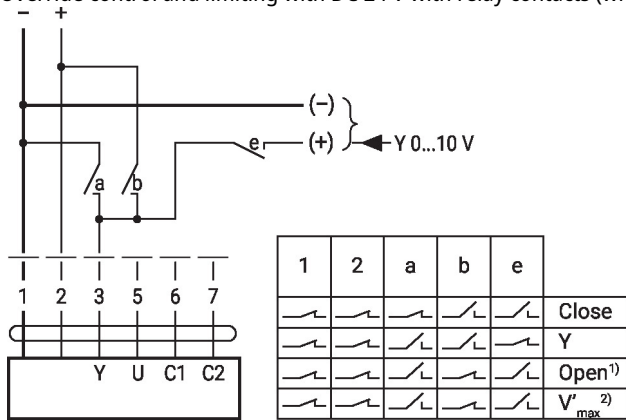
Override control and limiting with AC 24 V with relay contacts



**Functions**

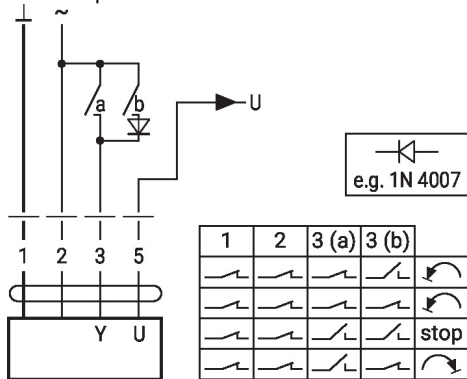
**Functions with specific parameters (parametrisation necessary)**

Override control and limiting with DC 24 V with relay contacts (with conventional control or hybrid mode)



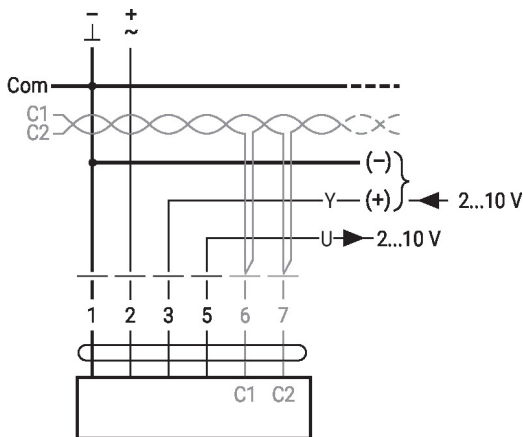
- 1) Position control
- 2) Flow control

Control 3-point with AC 24 V

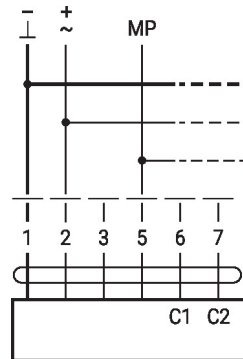


- Position control: 90° = 100s
- Flow control: V<sub>max</sub> = 100s

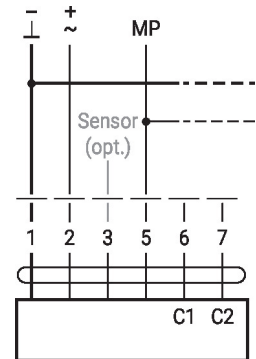
BACnet MS/TP / Modbus RTU with analogue setpoint (hybrid mode)



MP-Bus, supply via 3-wire connection

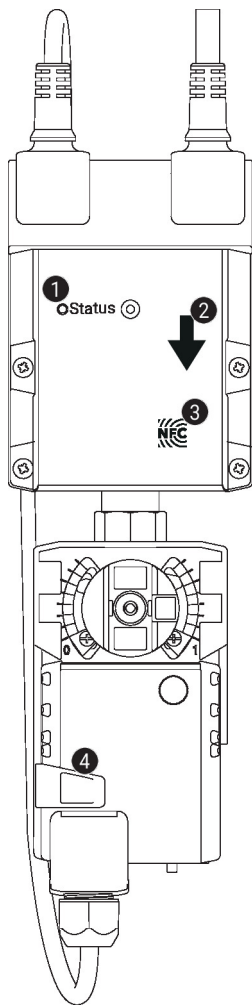


MP-Bus via 2-wire connection, local power supply





## Operating controls and indicators


**1 LED display green**

On:	Device starting up
Off:	No power supply or wiring error
Flashing:	In operation (Voltage ok)

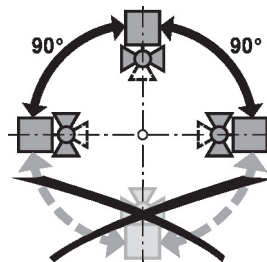
**2 Flow direction**
**3 NFC interface**
**4 Manual override button**

Press button:	Gear train disengages, motor stops, manual override possible
Release button:	Gear train engages, standard mode. Device performs synchronisation.

## Installation notes

**Permissible installation orientation**

The ball valve can be installed upright to horizontal. The ball valve may not be installed in a hanging position, i.e. with the spindle pointing downwards.


**Installation location in return**

Installation in the return is recommended.

**Water quality requirements**

The water quality requirements specified in VDI 2035 must be adhered to.

Belimo valves are regulating devices. For the valves to function correctly in the long term, they must be kept free from particle debris (e.g. welding beads during installation work). The installation of a suitable strainer is recommended.

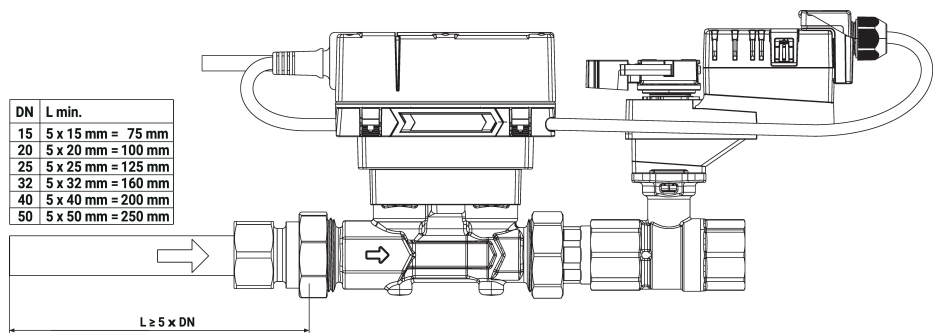
Installation notes

**Servicing** Ball valves, rotary actuators and sensors are maintenance-free.  
 Before any service work on the control element is carried out, it is essential to isolate the rotary actuator from the power supply (by unplugging the electrical cable if necessary). Any pumps in the part of the piping system concerned must also be switched off and the appropriate slide valves closed (allow all components to cool down first if necessary and always reduce the system pressure to ambient pressure level).

The system must not be returned to service until the ball valve and the rotary actuator have been correctly reassembled in accordance with the instructions and the pipeline has been refilled by professionally trained personnel.

**Flow direction** The direction of flow, specified by an arrow on the housing, is to be complied with, since otherwise the flow rate will be measured incorrectly.

**Inlet section** In order to achieve the specified measuring accuracy, a flow-calming section or inflow section in the direction of the flow is to be provided upstream from the flow sensor. Its dimensions should be at least 5x DN.



**Split installation** The valve-actuator combination may be mounted separately from the flow sensor. The direction of flow of both components must be observed.

General notes

**Minimum differential pressure (pressure drop)** The minimum required differential pressure (pressure drop through the valve) for achieving the desired volumetric flow  $V'_{max}$  can be calculated with the aid of the theoretical  $k_{vs}$  value (see type overview) and the below-mentioned formula. The calculated value is dependent on the required maximum volumetric flow  $V'_{max}$ . Higher differential pressures are compensated for automatically by the valve.

Formula

$$\Delta p_{min} = 100 \times \left( \frac{V'_{max}}{k_{vs \text{ theor.}}} \right)^2$$

$\Delta p_{min}: \text{kPa}$   
 $V'_{max}: \text{m}^3/\text{h}$   
 $k_{vs \text{ theor.}}: \text{m}^3/\text{h}$

Example (DN 25 with the desired maximum flow rate = 50%  $V'_{nom}$ )

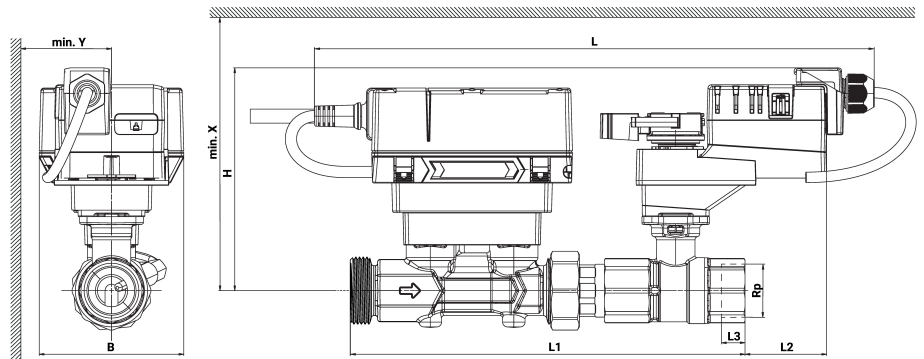
EP025R2+BAC  
 $k_{vs \text{ theor.}} = 8.8 \text{ m}^3/\text{h}$   
 $V'_{nom} = 58.3 \text{ l/min}$   
 $50\% * 58.3 \text{ l/min} = 29.2 \text{ l/min} = 1.75 \text{ m}^3/\text{h}$

$$\Delta p_{min} = 100 \times \left( \frac{V'_{max}}{k_{vs \text{ theor.}}} \right)^2 = 100 \times \left( \frac{1.75 \text{ m}^3/\text{h}}{8.8 \text{ m}^3/\text{h}} \right)^2 = 4 \text{ kPa}$$

**Behaviour in case of sensor failure** In case of a flow sensor error, the EPIV will switch from flow control to position control. Once the error disappears, the EPIV will switch back to the normal control setting.

## Dimensions

## Dimensional drawings



Type	DN	Rp ["]	G ["]	L [mm]	L1 [mm]	L2 [mm]	L3 [mm]	B [mm]	H [mm]	X [mm]	Y [mm]	kg
EP015R2+BAC	15	1/2	3/4	331	195	63	13	90	137	207	80	1.9
EP020R2+BAC	20	3/4	1	343	230	58	14	90	139	209	80	2.2
EP025R2+BAC	25	1	1 1/4	349	246	51	16	90	139	209	80	2.5
EP032R2+BAC	32	1 1/4	1 1/2	367	267	50	19	90	146	216	80	3.3
EP040R2+BAC	40	1 1/2	2	373	281	46	19	90	146	216	80	3.7
EP050R2+BAC	50	2	2 1/2	390	294	49	22	90	151	221	80	5.2

## Further documentation

- Tool connections
- BACnet Interface description
- Modbus Interface description
- Overview MP Cooperation Partners
- MP Glossary
- Introduction to MP-Bus Technology
- General notes for project planning
- Installation instructions for actuators and/or ball valves